MODULHANDBUCH

für den Studiengang der Fakultät Mobilität und Technik

Automotive Systems (Master) – SPO 2.0

Fassung 1.0 Stand 30.11.2022

Gültig ab Wintersemester 2023/2024



Änderungsverzeichnis

Datum	Version	Beschreibung der Änderung	Bearbeiter
30.11.2022	1.0	Modulbeschreibungen	Oberhauser

Hinweis zur Gültigkeit

Dieses Modulhandbuch gilt für Studierende, die das Studium im Studiengang

Automotive Systems SPO 2.0

der Studien- und Prüfungsordnung der Hochschule Esslingen ab dem WS23/24 aufgenommen haben.

Sonstige Anmerkungen

Der Workload pro Creditpoint beträgt in diesen Studiengängen (§8 (1) MRVO):

Credits	Workload in Stunden
1	30

Freigabe

Dieses Dokument ist freigegeben.

gez. Prof. Mathias Oberhauser



Kontaktpersonen Modulhandbuch

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Wahlmodule Vertiefung Automotive IT	
Automotive Communications	
Usability and Dependability	
Wahlmodule Vertiefung Vehicle Systems	Fehler! Textmarke nicht definiert.
Ride and Handling	Fehler! Textmarke nicht definiert.
Propulsion Systems	Fehler! Textmarke nicht definiert.
Nicht mehr angebotene Wahlmodule	Fehler! Textmarke nicht definiert.
Electric and Electronics Architecture	Fehler! Textmarke nicht definiert.
Packaging and Integration	Fehler! Textmarke nicht definiert.
Pflichtmodule drittes Semester	
Softskills	
Master Thesis	



Module erstes Semester

Mathematical Methods

1	Module Number 3901	Study Programme ASM	Semester 1	Offered in XWS □SS	Duration 1 Semester	Module Type compulsory	Workload (h) 240	ECTS Points -8
2	Courses			Teaching and Learning Forms		Contact Time		Language
					(SWS)	(h)	(h)	
	a) Numerical Ana	a) Numerical Analysis			3	45	120	English
		erential Equations	Lecture		2	30		0
	c) Statistics and Kalman Filter		Lecture		3	45		
						[1 SWS = 15h]		
3	Learning Outcomes Once the module ha	•		ne students can				
	• underst	derstanding the basic ideas of tand the algorithms tand the limitations	s and their con	straints	tand the relation	n to the applicat	ions	
	Use, Application an	d Generation of K	nowledge					
	 analyse recogni analyse familiar Scientific Innovati use met create i optimiz indeper develop Communication un interpression use the aspects. commu Scientific Self-Concernation	he algorithms in M. the solutions cond ze and classify con- technical problem rize themselves with ion thods and tools to new models. the systems. Indently develop ap to concepts for the of d Cooperation et the results of nu- learned knowledg unicate and cooperation	erning plausibi nections. Is and derive or h new ideas an gain new insigh proaches for no optimization of merical analysis e, skills and cor ate within the g alism	develop soluti d topics based ats in the field of ew concepts ar technical appli s and draw adn mpetences to e group in order t	on their basic kr If numerical ana Id assess their su cations. hissible conclusio valuate the field	lysis. uitability. ons. and interpret th	-	o other
4	RegrNum	ar systems ession erical differentiatio inear equations an	•					
		nary differential eq al differential equa						ications)

MODULE ERSTES SEMESTER – MATHEMATICAL METHODS



	 Descriptive and inferential statistics Probability theory Kalman filter
	Programming in MATLAB as part of the lecture.
5	Participation Requirements
	compulsory: - recommended: Good knowledge of further mathematics
6	Examination Forms and Prerequisites for Awarding ECTS Points
	Written Examination, 120 minutes
7	Further Use of Module Applying mathematical methods in other lectures and major fields of automotive engineering
8	Module Manager and Full-Time Lecturer
	Prof. Dr. J. Gaukel, Prof. Dr. M. Stämpfle, Prof. Dr. G. Schaaf
9	 Literature Gander W., Gander M.J., Kwok, F., Scientific Computing Stanoyevitch, Introduction to Numerical Ordinary and Partial Differential Equations Using MATLAB, Wiley Marchthaler, Dingler: Kalman-Filter: Einführung in die Zustandsschätzung und ihre Anwendung für eingebettete Systeme Chui, Chen: Kalman Filtering, Springer
10	Last Updated 06.10.2022



System Design

1	Module Number Stud 3902	dy Programme ASM	Semester 1	Offered in XWS ⊡SS	Duration 1 Semester	Module Type compulsory	Workload (h) 240	ECTS Point 8
2	Courses		Teaching and Learning Forms		Cont	Contact Time		Language
					(SWS)	(h)	(h)	
	a) Automotive System	n and	Lecture		4	60	120	English
	Software Architect						[bitte nur	8
	b) Automotive System	ns	Lecture		4	60	Summe	
	Development Proce		Lecture		4		eintragen]	
	System Test					[1 SWS = 15h]		
3	Learning Outcomes and							
	Once the module has be					iated hardware	and coffware ar	chitacturac
		n solutions in t						lintectures
					d on a clear und	lerstanding of th	e required desig	zn and
		processes nece						.
	Knowledge and Unders	tanding	-					
			re of automotiv	e electric and	electronic system	ms and their dev	elonment proce	200
	know the lin		systems, have			the automotive		
	Use, Application and Ge	eneration of Kr	nowledge					
	Lies and Transfer							
Use and Transfer understand the complete automotive system developme			nt process inclu	ding system test	and application	`		
						ir respective dev		
						r software archit		
		on principles an			,			
					bandwidth and	atency.		
		ssess the safet		•				
	• compare au	tomotive solut	ions with solut	ions and conce	pts from other t	echnical domain	S.	
	Scientific Innovation			**				
		ls and tools to g			implementatio	a and tests		
						ty, performance	nohustness an	nd cost
						d validate the E/		
						tability, especial	-	ed technical
						uter science into		
	Communication und Co	•						
		te actively with						
		e results of the				contrand access	their features	
		omotive syster				cepts and assess	then reatures.	
			-			d adequate solut	ions for the tasl	k at hand.
	Scientific Self-Conception	on/ Profession	alism					
						tion of the socie		
					erspective on th	e basis of the ar	alyses and eval	uations mad
	 … justify the s … reflect and s 	olution theoret						



4	Contents Lecture a): System Development
	Typical components and functions of automotive systems.
	 Typical engine management system and its development process.
	 Software life cycle including classic V model, agile (Scrum) development and Automotive Spice.
	Requirements engineering and requirements management.
	 SW-documentation and data specification, coding guidelines.
	Software and system test.
	Application examples of simple functions
	Lecture b):
	• Application domains powertrain, chassis, body, advanced driver assistance, infotainment, outlook to automated driving
	Basics of distributed systems. ECU hardware requirements and structure, communication relations and communication problems under real-time constraints.
	• E/E architecture of hybrid and electric powered cars vs. cars with classic combustion engines. Trend towards domain controller and compute-server-architectures.
	 Automotive bus systems and communication protocols (CAN, LIN, FlexRay, MOST, Automotive Ethernet, V2X). Message based communication vs. service oriented communication.
	Diagnosis and diagnostic communication.
	Qualitative and quantitative assessment of system safety and reliability. Functional safety including ISO 26262.
	ECU software architecture and software standards (AUTOSAR Classic and Adaptive)
	The lectures will include theory, case studies, literature surveys and presentation of selected topics done by student teams.
5	Participation Requirements
	compulsory: -
	recommended:
	Basic knowledge in electronics and computer science. Familiarity with one of the major programming languages, C/C++ preferred.
	Own experience in self-management of a project, i.e. Bachelor thesis
6	Examination Forms and Prerequisites for Awarding ECTS Points
Ū	Written Examination 120 min
7	Further Use of Module
	Autonomous Systems, Propulsion Systems, Team Project, Master Thesis
8	Module Manager and Full-Time Lecturer
	Prof. Dr. W. Zimmermann
9	Literature
	J. Schäuffele, T. Zurawka: Automotive Software Engineering. Springer-Vieweg.
	 H. Wallentowitz, K. Reif: Handbuch Kraftfahrzeugelektronik. Springer-Vieweg.
	 R.K. Jurgen. Automotive Electronics Handbook. McGraw-Hill.
	 W. Zimmermann, R. Schmidgall: Bussysteme in der Fahrzeugtechnik, Springer-Vieweg.
	 K. Reif (Publisher): Bosch Automotive Handbook Series. Springer-Vieweg.
10	Last Updated 2022-10-10



Simulation and Control

1	Module Number 3903	Study Programme ASM	Semester 1	Offered in XWS □SS	Duration 1 Semester	Module Type compulsory	Workload (h) 240	ECTS Points 8
2	Courses		Teaching and Learning Forms		Cont	Contact Time		Language
					(SWS)	(h)	(h)	
	a) Microcontrolle Simulation	er, Modelling and	Lecture + Lab		2+1	45	120	Englisch
	b) Basic Control	b) Basic Control			2	30 45		
	c) Advanced Cont	trol	Lecture		3	[1 SWS = 15h]		
3	Learning Outcomes Once the module ha			ne students can		I		
	 … know h 	derstanding tand and know the ow and where to u p basic control loop	ise these metho	ods in the devel	opment of auto		gineering	
	Use, Application an	d Generation of K	nowledge					
 Use and Transfer apply physical laws to derive mathematical system models in different domains (mechanical, electrical, the apply methods of system simulation and control engineering in automotive applications analyse and evaluate the behaviour of automotive systems and subsystems by use of simulation results develop small circuits with sensors and actuators and develop programs for Microcontroller, build up, test calibrate control functions Scientific Innovation use simulation and control engineering methods and tools to gain new insights into automotive systems or subsystems. create and optimize the behaviour of automotive systems based on system models 								
					sor			
	• get acq	uainted with pract	ical realization	of the simulated	d problem in a n	nicrocontroller e	nvironment	
	Communication un	•						
 create, communicate and discuss technical information's in the area of the course subject communicate actively within an organization and obtain information. 								
	Scientific Self-Conc							
 justify the solution theoretically and methodically to improve development methods. reflect and assess one's own abilities in a group comparison. 								
4	Contents							
		ntroller, Modelling						
		ic System Modellin						
		ensors and actuator			•	transter functio	n	
	_	on of Control loops						
		ion of sensors / act ations using Simulir						
	 Build up s AutoCodir 	small control system ng (Simulink to Ard	n examples in H luino)	lardware and tr	ansfer control a	-		ment and do
	Compare	pure Simulink/Sim	scape Simulatio	on with the Syst	em realized in H	ardware with M	licrocontroller	

MODULE ERSTES SEMESTER - SIMULATION AND CONTROL



	 Elements of control loops Linearization of nonlinear differential equations Laplacetransformation (Definition,rules,examples) Basic Controllers (PID) Bode diagramm Stability, Nyquist criteria, amplitude margin, phase edge Root locus
	 2. Advanced Control I (3h) Linear and non-linear State Space Representation State Space Controller Design (Pole Placement) Observer Design and Separation Theorem Digital Control / Discrete State Space Design LQR-Controller Design Diskretisierung, Matrix Exponentionalfunktion
	 3. Computer Lab (1h) System Representations using Matlab/Simulink, Numerical Simulation Modelling/Identification and Controller Design of an Electric Drive System Controller Design of an Electric Drive System System Modelling and Simulation of State Machines → System Design
5	Participation Requirements compulsory: Mathematics, Physics, Mechanics , Control Engineering Basics recommended: Basics in Matlab/Simulink
6	Examination Forms and Prerequisites for Awarding ECTS Points Written Examination, 120 minutes
7	Further Use of Module Autonomous Systems, Propulsion Systems, Team project, Master Thesis
8	Module Manager and Full-Time Lecturer Prof. DrIng. Walter Lindermeir , Prof. Mathias Oberhauser, Prof. Georg Mallebrein
9	Literature Lecture Notes and Scripts Ogata, K.: Modern Control Engineering, Pearson Verlag Liu, Xiangjie: Systems Control Theory, Science Press Beijing Palm, W. J.: MATLAB for Engineering Applications, McGraw-Hill Hanselman D.C., Littlefield B.: Mastering Matlab, Pearson Verlag Dabney, J.B.; Harman, T.L.: Mastering Simulink Mohthari: Engineering Applications in Process Control, Fuzzy Control
10	Last Updated 18.10.2022



Vehicle System Fundamentals

	Module Number 3904	Study Programme ASM	Semester 1	Offered in XWS □SS	Duration 1 Semester	Module Type compulsory	Workload (h) 180	ECTS Points 6
2	Courses		Teaching and Learning Forms		Contact Time		Self-Study Time	Language
					(SWS)	(h)	(h)	
	a) Motor Vehicles	5	Lecture		3	45	90	Englisch
	b) Introduction to Propulsion	vehicle	Lecture		2	30		-
	c) Lab Motor Veh	icles	Lab		1	15		
3	Learning Outcomes							
	Once the module ha	as been successfull	y completed, tł	ne students can.				
	Knowledge and Un	derstanding						
	electric describ describ explain underst on ene	the basic terms in and hybrid vehicle e the different pow e the different veh basic component p tand and calculate rgy consumption	s vertrain topolog icle drivetrain c parts of the cha rolling resistan	gies like conventions lists and the driving and the driving and the driving a convention of the driving a conventi	tional, hybrid ar ike front wheel, /e train ic drag, climbing	nd battery- as we rear wheel and g and acceleration	ell as fuel cell el 4-wheel-drive on resistance ar	ectric nd their impa
	• gain a	first knowledge of t	transversal ven	icle system simi	liation including	torques, power	rs and energy fid	ows
	Use and Transfer choose create 	the best engine an testing reports and	Seneration of Knowledge e best engine and driveline combination for different types of vehicles. ting reports and present test results. The state of the art wheel suspension systems d the physical behaviour of forces between road and tyre for vehicle dynamics simulation themselves with new ideas and topics in the field of automotive powertrains and suspensions ifferent powertrain topologies and their performance and efficiency					
	familiar	ize themselves wit						S
	Scientific Innovat	ion		Scientific Innovation				
	 find new 							
	 optimiz set up r calibrat 	w technologies to le e powertrains for h new driving test pro e tyre models to m ndently develop ap	nigh driving per ocedures and e leasurements	formance xperience energ				
	 optimiz set up r calibrat 	e powertrains for h new driving test pro e tyre models to m ndently develop ap	nigh driving per ocedures and e leasurements	formance xperience energ				
	 optimiz set up n calibrat independent Communication un communication un interpresent 	e powertrains for h new driving test pro e tyre models to m ndently develop ap	high driving per pocedures and e leasurements proaches for no hin a research o hicle testing an	formance xperience energ ew suspension a pr development d draw admissik	and driveline con team and obtai ple conclusions.	ncepts and asse		
	 optimiz set up n calibrat independent Communication un communication un interpresent 	e powertrains for h new driving test pro- e tyre models to m ndently develop ap d Cooperation unicate actively with et the results of vel- unicate with power	high driving per pocedures and e leasurements proaches for no hin a research o hicle testing an train and chass	formance xperience energ ew suspension a pr development d draw admissik	and driveline con team and obtai ple conclusions.	ncepts and asse		
	 optimiz set up n calibrat independing Communication un communication un interpresent communication un Scientific Self-Conce derive n analyse 	e powertrains for h new driving test pro- e tyre models to m ndently develop ap d Cooperation unicate actively with et the results of vel- unicate with power	high driving per ocedures and e leasurements proaches for no hin a research o hicle testing an train and chass alism for decisions fro made.	formance xperience energe ew suspension a pr development d draw admissik sis designers abo pm an environm	and driveline con team and obtai ole conclusions. out new solution	ncepts and asse n information.	ss their suitabili	ty.

MODULE ERSTES SEMESTER – VEHICLE SYSTEM FUNDAMENTALS



	a)	Lecture: Motor Vehicles
		The course gives a basic knowledge in vehicle technology and their components The power train is mainly focused The aim is to learn the ability to calculate driving resistance and to design the power train with respect to driving performance and fuel consumption
	b)	Introduction to Vehicle Propulsion
		Internal Combustion Engine (Ice) and Engine Control Fundamentals, including trends of the Ice. Alternative Powertrains: Ice-Hybrid, Battery-Electric Vehicle, Fuel-Cell Electric Vehicle and their specific components (Battery, Fuel-Cell, Electric Motor) Longitudinal vehicle Simulation (Simulink), consumption and performance (torque, power, energy flows)
	c)	Lab: Motor Vehicles
		Determination of full-load torque and power pattern by using the car test bench Detection of fuel consumption map
		Determination of a tyre map by using the tyre test bench EUREPA. Analysis of vehicle road tests
5	Par	ticipation Requirements
		npulsory: no ommended: Fundamentals of Engineering Mechanics
6	Exa	mination Forms and Prerequisites for Awarding ECTS Points
	Wri	tten Examination 120 Minutes
7	Fur	ther Use of Module
	Pro	pulsion Systems
	Теа	m Project
8	Мо	dule Manager and Full-Time Lecturer
	Pro	f. Dr. Holtschulze
9		rature
	-	wood, J.B. Internal Combustion Engine Fundamentals McGraw-Hill SCH Automotive Handbook Distribution SAE
10		t Updated 10.2022



Pflichtmodule zweites Semester

Autonomous Systems

1	Module Number 3906	Study Programme ASM	Semester 2	Offered in WS XSS	Duration 1 Semester	Module Type compulsory	Workload (h) 240	ECTS Points 8		
2	Courses		Teaching and Forms	Learning	Conta	act Time	Self-Study Time	Language		
					(SWS)	(h)	(h)			
	a) Mobile Roboti	cs	Lecture		4	60	120	Englisch		
	b) Sensors		Lecture		2	30	[bitte nur	Ū		
	c) Data Fusion		Lecture		2	30	Summe			
					-	[1 SWS = 15h]	eintragen]			
3		as been successfull in the fields of mot derstanding nd sensor principles	y completed, th bile robotics an s and sensor sig	d self-driving ve gnal processing	hicles.	n, implement a	nd evaluate auto	pnomous		
		nd how to retrieve most important co				eir requirement	ts and their mod	e of operatio		
 Use, Application and Generation of Knowledge Use and Transfer apply fundamental techniques and algorithms to fuse raw signals of different sensors apply fundamental techniques and algorithms of a mobile robotics software system analyze and develop solutions to real-world problems Scientific Innovation 										
	 develop novel approaches using state of the art statistics and filtering methods develop novel approaches using state of the art machine learning methods, e.g. deep neural networks 									
	 Communication und Cooperation communicate actively within a development team with engineers from other disciplines present technical contents and discuss them 									
	in present									
	Scientific Self-Conc	eption/ Profession	alism							
	0	and implement sof	0		,					
_		e different sensor o	configurations a	and autonomou	s driving system	architectures				
4	Contents	a Dahatiaa								
	Lecture: Mobil	ion to mobile robot	tics and automs	ated driving						
				-	'n					
	 Machine learning and sensor-based environment perception Mapping and localization 									
	 Action and motion planning 									
	Design and architecture of mobile autonomous systems									
	Lecture: Senso	vrs								
		chnology (Radar, L	idar, Camera)							
	Sensor Ra	ıw Data								
	Data Sets									
	Data Fusion									



	 Basics Statistics, Kalman filter (KF) an application for automated driving From sensor data to tracked objects, e.g. Point cloud data, segmentation and clustering
5	Participation Requirements
	compulsory: no
	recommended:
	undergraduate course in physics undergraduate course in computer science, programming in C/C++ or Python module ASM 3901 (Mathematical Methods in Engineering) module ASM 3902 (Simulation and Control)
6	Examination Forms and Prerequisites for Awarding ECTS Points
	Written Examination 120 Min
7	Further Use of Module
	Master Thesis
8	Module Manager and Full-Time Lecturer
	Prof. Dr. Ralf Schuler, Prof. Dr. Markus Enzweiler, Prof. Dr. Clemens Klöck, NN
9	Literature
	Sebastian Thrun et al.: Probabilistic Robotics. MIT Press, 2005.
	Richard Szeliski.: Computer Vision: Algorithms and Applications, 2022.
	RaJ, A. (Jun 28, 2002). Euclidean Clustering for Lidar point cloud data.
	RaJ, A. (Jun 6, 2002). 3D RANSAC Algorithm for Lidar PCD Segmentation.
	Maybeck, P.S. (1979). Chapter 1, "Introduction" from STOCHASTIC MODELS, ESTIMATION, AND CONTROL, Volume 1. Academic Press, 1979.
10	Last Updated 05.10.2022



Team Project

1	Module Number 3907	Study Programme ASM	Semester 2	Offered in WS X SS	Duration 1 Semester	Module Type compulsory	Workload (h) 240	ECTS Point 8		
2	Courses		Teaching and Forms	Learning	Cont	tact Time	Self-Study Time	Language		
	Team Project		Project work		(SWS) 3-1	(h) 4 5 15 [1 SWS = 15h]	(h) 165-225	Englisch		
3	Learning Outcomes and Competences Once the module has been successfully completed, the students can									
	 Knowledge and Understanding develop a project plan split complex tasks into subtasks. apply the knowledge from lectures and labs on a real application. understand the limitations of project time and human resources. 									
	Use, Application and Generation of Knowledge Use and Transfer use methods and tools of project management understand the principles of systems engineering.									
	 work with state of the art engineering software and measurement equipment. Scientific Innovation describe interfaces of complex systems. apply scientific methods to solve industrial problems. discuss pros and cons of new solutions in a group. interpret measurement data and simulation results. 									
	 Communication und Cooperation work together according to a project plan take into account cultural differences in working style, leadership and communication. cooperate within the group in order to find adequate solutions for the project task. 									
	 Scientific Self-Conception/ Professionalism work successfully in international development groups in industry. 									
4	Contents									
	application of project management									
	 constitution of hierarchy (project-manager, teams members) 									
	 constitution of project structure (time schedule, work packages 									
	 realisation of given task 									
	documentation and evaluation of results									
	• presentation of results									
	 project feedb 	ack								
5	Participation Requi compulsory: - recommended: Lec	irements								



6	Examination Forms and Prerequisites for Awarding ECTS Points
	Presentation in a group , 20 minutes Group report
7	Further Use of Module
	Preparation for Master thesis
8	Module Manager and Full-Time Lecturer
	Prof. Mathias Oberhauser
9	Literature •
10	
	23.04.2019 -10.10.2022



Wahlmodule Vertiefung Automotive IT

Automotive Communications

1	Module Number 3908	Study Programme ASM	Semester 2	Offered in WS XSS	Duration 1 Semester	Module Type compulsory	Workload (h) 210	ECTS Point 7			
2	Courses		Teaching and Learning Forms		Cont	Contact Time		Language			
					(SWS)	(h)	(h)				
	a) Communicatio	n Systems	Lecture		3	45	105	English			
	a) communicatio	II Systems	Lecture		5	45	105	Eligiisii			
	b) Vehicle-to-X (V	2X)	Lecture		4	60					
						[1 SWS = 15h]					
3	Learning Outcomes Once the module ha			ne students can							
	Knowledge and Un	derstanding									
	-	etwork architectur									
		and wired and wir hend use cases and				elevant for vehic	ular networks.				
	Use, Application an	d Generation of K	nowledge								
	Use and Transfer										
			omotive comm	unication tech	nologies.						
	 setup a 	 design and implement automotive communication technologies. setup and configure networked devices in a vehicle. 									
	Scientific Innovat	Scientific Innovation									
	evaluate the suitability of different technical solutions.										
	• use me	asurements and/or	r simulation too	ols to analyse au	itomotive comm	nunication.					
	Communication and	d Cooperation									
		inicate actively wit	hin an organiza	tion and obtain	information.						
		t technical contents	-								
• communicate and cooperate within the group to find adequate solutions for the task at hand.						hand.					
	 Scientific Self-Conception/ Professionalism derive recommendations for decisions from a social and ethical perspective based on analysis and evaluation. 										
		econimentations			ethical perspect						
4	Contents Lecture a): Commu	nication systems									
		als of communicat	ion networks								
		nd TCP/IP basics									
		ommunication sys									
	Automotive										
	Selected applications (e.g., SOME/IP)										
	Lecture b): Vehicle-to-X (V2X)										
		ntals of radio comr									
		nmunication techn	ologies (e.g., 50	5, IEEE 802.11p							
		ntals of safety encoding (e.g., ASN	11)								
	-	o-X (V2X) motivatio		s							
	 V2X mess 	· /		-							
		orking (e.g., addre	ssing, routing)								
	 V2X applie 										



	Simulation tools
	Privacy and security for V2X
	Participation Requirements
	compulsory: -
	recommended:
	Basics of communication systems and computer networks,
	Knowledge of a programming language, preferably C/C++ and/or Java
6	Examination Forms and Prerequisites for Awarding ECTS Points
	Written Examination 120 min
7	Further Use of Module
	Master Thesis
8	Module Manager and Full-Time Lecturer
	Prof. DrIng. M. Scharf, Prof. Dr. D. Schoop, Prof. DrIng. H. Melcher
9	Literature
	 Andrew S. Tanenbaum, Nick Feamster, David Wetherall, "Computer Networks", 6th Edition, Pearson, 2021 James F. Kurose, Keith W. Ross, "Computer Networking: A Top-Down Approach", 7th edition, Pearson, 2016 Kirsten Matheus, Thomas Königseder, "Automotive Ethernet", Cambridge University Press, 2015 Christoph Sommer, Falko Dressler, "Vehicular Networking", Cambridge University Press, 2014 Standards of the European Telecommunications Standards Institute (ETSI), Intelligent Transport Systems (ITS)
10	Last Updated 11. Oct.2022



Usability and Dependability

1	Module Number 3909	Study Programme ASM	Semester 2	Offered in WS XSS	Duration 1 Semester	Module Type compulsory	Workload (h) 210	ECTS Points 7
2	Courses	Teaching and Learning Contact Time Forms		act Time	Self-Study Time	Language		
					(SWS)	(h)	(h)	
	a) Safety and Sec	urity	Lecture		3	45	105	Englisch
	b) Automotive M	-	Lecture		4	60		-
	Interaction (M	MI)				[1 SWS = 15h]		
3	Learning Outcomes Once the module ha	-		ne students can.		I		
	Knowledge and Un	derstanding						
	 understand usability, user experience (UX), and users'/drivers' requirements and project management issues in the development of automotive applications understand safety and security issues in the development of automotive applications 							
	Use, Application ar	nd Generation of Ki	nowledge					
	Use and Transfer							
		tand and apply requ			cumentation			
		tand and evaluate e ient and test a prot						
		tand usability and l			SO 9241			
		esentations of proje	-					
	• unders	tand the main cond	epts: safety, fu	inctional safety,	security, inform	nation security.		
		tand the main conc						
		re of security threa		notive domain				
		tand security risk m	-					
		tand the main conc tand safety manage		ig to ISO 26262				
	Scientific Innovat							
	use methods and tools to gain new insights in the field of usable and dependable automotive systems							
	Communication und Cooperation							
communicate actively within an organization and obtain information								
	present technical contents and discuss them regularly							
	communicate and cooperate within the group to find adequate solutions for the task at hand							
	Scientific Self-Conc	eption/ Profession	alism					
		recommendations f		om a social and	ethical perspect	tive based on th	e analyses and e	evaluations
4	Contents							
	Lecture a): Safety a	and Security						
		epts: safety, functio	onal safety, sec	urity, informatio	n security			
		epts in security						
		reats in the automo		.g.				
	o li	nsecure bus system	IS					
	• C	hip manipulation						
	o C	Component theft						



	• Evading access controls
	Counter measures based on cryptography
	Security risk management
	Safety and Security in vehicular ad hoc networks (VANETs)
	Main concepts in safety
	Safety management according to ISO 26262
	Lasture b). Automotive Man Masking Internation (MANAI)
	Lecture b): Automotive Man Machine Interaction (MMI)
1	 Basics terms and concepts of man machine interaction, requirements of graphical user interfaces, design requirements (software ergonomics, usability, dialog principles). On-board Pattern Recognition Systems.
	 machine vision systems (e.g. in traffic monitoring and automatic congestion detection, in driver assistance systems, for gesture recognition)
	• speech communication: speech recognition and understanding systems, speech dialogs: speech synthesis and language
	generation (Human-Machine Interface).
	 usability engineering, testing and evaluation of recognition systems
	Driver Assistance Systems
	 concepts for programming of driver assistance systems in automobiles: environment models, interpretation and fusion of sensor data, piloting functions, cooperative concepts.
	 implementation of important concepts in laboratory – user-centered design
	Human Factors Engineering
	human factors, such as vision, cognition
	driver attention and distraction
	usability, user-centered design, UX
	multimodal Interfaces Lab (programming exercises and presentations, simulation)
	Project
	selected tasks and semester project (group work)
	Participation Requirements
	compulsory: -
	recommended:
	C/C++ programming
	computer networks basics
	object oriented modelling (UML)
	software engineering
6	Examination Forms and Prerequisites for Awarding ECTS Points
	Written Examination 120 min
7	Further Use of Module
	Master Thesis
8	Module Manager and Full-Time Lecturer
	Prof. A. Beck, Prof. Dr. D. Schoop,

WAHLMODULE VERTIEFUNG AUTOMOTIVE IT - USABILITY AND DEPENDABILITY



9	Literature	
	• • •	Shiho Kim, Rakesh Shrestha, Automotive Cyber Security Introduction, Challenges, and Standardization, Springer, 2020 Christof Paar, Embedded Security in Cars, 2005 Hans-Leo Ross, Safety for Future Transport and Mobility, Springer, 2021 ISO 26262 ("Road vehicles – Functional safety") DIN EN ISO 9241 ("Ergonomics of human-system interaction")
10	Last Update 16 Oct 2022	



Pflichtmodule drittes Semester

Softskills

1	Module Number 3914	Study Programme ASM	Semester 1	Offered in WS	Duration 1 Semester	Module Type compulsory	Workload (h) 210	ECTS Points 7	
2	Courses		Teaching and Forms	Learning	Cont	act Time	Self-Study Time	Language	
					(SWS)	(h)	(h)		
	a) Global Enginee	ering	Lecture		2	45	105	Englisch	
	b) Project Manag	-	Lecture		2	45		0.00	
	c) International N		Lecture		2	45			
		egotiations	Lecture		2	45 [1 SWS = 15h]			
3	Learning Outcomes Once the module has Knowledge and Un	as been successfull		he students can					
	 understand sales & marketing aspects of global engineering projects. understand different approaches towards global engineering projects (waterfall, agile, hybrid project management). develop a project plan, split complex tasks into subtasks. apply the knowledge from lectures and labs on a real application. understand the limitations of project time and human resources. know about Intellectual properties and patent topics in engineering know cultural differences. improve language and mimic as a tool of successful interaction understand mechanisms of multilateral business and trade formals Use and Transfer be able to choose the right right engineering approach in relation to the market needs use methods and tools of project management. understand the principles of Global Engineering. 								
 interpret gantt-charts, calculate the time and financial aspects of projects. include and consult IP and patent experts in a professional manner – and know when appropriate use state-of –the-art software support for projects apply the gained knowledge to case-studies. improve cooperation within your own unit / company improve company - customer relationships come to better results with international partners being able to estimate the economic impact of IPR transfer engineering results to production 									
	 Scientific Innovat • describ • apply s		of R&D, produc o solve enginee	ction, sales & fir ering tasks.		5.			
	take int	ogether according to account cultural	differences in v	working style, le		ommunication. solutions for the	a nroject task		



	lead project teams
	achieve more satisfying business output of international negotiations
	 use the right negotiation options according to the specific (cultural) counterparts
	 … handle difficult situations and settle conflicts peacefully
	Scientific Self-Conception/ Professionalism
	work successfully in international development groups in industry.
4	Contonto
4	Contents
	a) and b) (Global Engineering & Project Management)
	Sales & Marketing Aspects of Engineering Projects
	 Project lifecycle and analysis
	- Branding
	- Key Account Management
	- Customer Management
	- Bid management
	Intellectual Property and Patents
	- Basics of Intellectual Property Rights (IPR)
	 Global Corporate Patent Strategy and Management
	 Global collporate Patent strategy and Management Company examples
	Classical Project Management
	 Project Management Processes Functions and responsibilities of a project manager
	 Scope, Time, Quality & Risk Management
	 Scope, Thie, Quality & Kisk Management Communications, HR & Integration Management
	Documentation, reporting, presentation, decision making Agile and Hybrid Project Management
	Agile and Hybrid Project Management Overview of different agile methods
	- Overview of different agile methods
	- Scrum
	Integration of classical and agile methods Critical Chain Project Management (CCDM)
	Critical Chain Project Management (CCPM) Camification with theoretical inputs
	- Gamification with theoretical inputs
	 application of project management to a case study Supporting IT structures
	Supporting IT structures IT Network and Infrastructure
	- IT Organisation
	- IT Security
	- Managing Product Data
	 From Engineering to Production
	c) International Negotiations
	Background teaching of cultural differences
	Interactive / international role plays
	• Exchanging of experiences of business and other cross-cultural transactions and achievements / failures.
	 Discourse and examples aimed at improving individual skills / arguments.
	Win-win situations – learning different methods of negotiations
	Participation Demoissments
	Participation Requirements
	compulsory: -
	recommended: Negotiation English
	Some basic business experience
	Basic multicultural skills
6	Examination Forms and Procequicites for Awarding FCTS Points
б	Examination Forms and Prerequisites for Awarding ECTS Points 120 min written exam
7	Further Use of Module
,	Module Team Project, Preparation for Master thesis, Preparation for negotiations in job situations
	module real rojec, reputation for musici acos, reputation for negotiations in job situations



Module Manager and Full-Time Lecturer
Prof. Dr. Siegfried Zürn - plus external experts and lecturers
Literature
 Script and case studies will be provided in electronic format
PMBOK Guide 8 th edition, PMI Institute
 Larson, E.W.; C.F. Gray (2016): Project Management – The Managerial Process, McGraw-Hill
 Mühlen, Alexander (2010): International Negotiations, Münster Verlag, 2010
Last Updated
2022-10-10



Master Thesis

1	Module Number 3915	Study Programme ASM	Semester 3	Offered in X WS SS	Duration 1 Semester	Module Type compulsory	Workload (h) 690	ECTS Points 23
2	Courses		Teaching and Learning Forms		Contact Time		Self-Study Time	Language
					(SWS)	(h)	(h)	
	Master Thesis		Thesis		2	30	600	Englisch
	Master Thesis Presentation and Defence		Presentation		1	15	45	
3	3 Learning Outcomes and Competences Once the module has been successfully completed, the students can							
	 Knowledge and Understanding handle and solve a problem with scientific methods on their own 							
	Use, Application and Generation of Knowledge							
	Use and Transfer							
		do scientific literature research .						
	 write a scientific report. give a presentation about thesis results. 							
	 give a presentation about thesis results. organize themselves. 							
	Scientific Innovation Scientific Innovation		nd their limitat	tions in there er	igineering discip	line.		
	 understand the theories and their limitations in there engineering discipline. find new solutions. Communication und Cooperation 							
	give comprehensive intermediate reports to supervisors.							
	work together with technical staff in industrial labs.							
	cooperate within their own department and other departments and suppliers.							
	Scientific Self-Conception/ Professionalism							
	work in R&D departments in industry							
	join a PhD program							
4	Contents							
	 constitution of project structure (time schedule, work packages) realisation of given task with scientific methods and within a given timeframe 							
	documentation and evaluation of results							
	 presentation 	presentation and defense of results						
5	Participation Requ	irements						
	compulsory: -	compulsory: -						
	recommended: Lectures and labs of first and second semester, team project							
6	Examination Forms	Examination Forms and Prerequisites for Awarding ECTS Points						
	Presentation and and oral examination , 30 minutes							
	Thesis report							



7	Further Use of Module			
	Preparation for Master thesis			
8	Module Manager and Full-Time Lecturer			
	Prof. Mathias Oberhauser			
9	Literature			
	•			
10	Last Updated			
	23.04.2019			